

Amendments to the Claims:

The listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

Claim 1. (Currently Amended) ~~A device with a unit (10) which is provided so as to activate an especially continuously~~ Apparatus for controlling activation of an adjustable drive unit $[(11)]$ of a motor vehicle $[(12)]$ dependent upon at least one control signal; wherein: ~~(α, α_{virt}) and at least in one phase (T) to produce~~

at least during a constant driving mode a virtual control signal ~~(α_{virt}) and instead to use~~ is generated in addition to a real control signal, $[(\alpha)]$ for activating the drive unit; $[(11)]$

~~characterized by the fact that,~~

~~the unit (10) is equipped so as to activate~~ during the constant driving mode the drive unit (11) ~~at least in a constant driving mode, in which the unit (10) maintains a constant driving force of the motor vehicle through an appropriate selection of the control signals (α_{virt}) , is activated~~ dependent upon the virtual control signal $[(\alpha_{virt})]$ instead of the real control signal; and

during the constant driving mode, the apparatus maintains a constant driving force of the motor vehicle through an appropriate selection of the control signals .

Claim 2. (Currently Amended) ~~A device~~ The apparatus according to claim 1, ~~characterized by the fact that the unit (10)~~ wherein a unit for determining a constant virtual control signal $[(\alpha_{virt})]$ is provided.

Claim 3. (Currently Amended) ~~A device~~ The apparatus according to claim 1, ~~characterized by the fact that the unit (10) for determining~~ 2, wherein determination of the virtual control signal (α_{virt}) dependent depends upon a real control signal $[(\alpha)]$ at a switch on point (t_2) of the constant driving mode ~~is provided.~~

Claim 4. (Currently Amended) ~~A device~~ The apparatus according to claim 3, ~~characterized by the fact that~~ 3, wherein the virtual control signal $[(\alpha_{virt})]$ at the switch on point $[(t_2)]$ is equal to the real control signal $[(\alpha)]$

Claim 5. (Currently Amended) ~~A device~~ The apparatus according to any of the foregoing claims, ~~characterized by the fact that~~ claim 4, wherein the unit (10) ~~for switching on and switching off~~ switches the constant driving mode on and off, dependent upon a time course of a real control signal $[(\alpha)]$ ~~is provided.~~

Claim 6. (Currently Amended) ~~A device~~ The apparatus according to claim 5, ~~wherein characterized by the fact that~~ the unit ~~[(10)]~~ is ~~provided as to switch-off~~ switches the constant driving mode off when the real control signal ~~(α)~~ ~~exits an~~ exceeds a set interval, ~~[(I_a)]~~

Claim 7. (Currently Amended) ~~A device~~ The apparatus according to ~~any of the foregoing claims, characterized by the fact that~~ claim 1, wherein the unit ~~(10) is provided to switch-off~~ switches the constant driving mode off when the speed change rate ~~speed-(α')~~ of the real control signal exceeds a set ~~(α) leaves an interval~~, ~~[(I_a)]~~

Claim 8. (Cancelled)

Claim 9. (New) The apparatus according to claim 1, wherein said drive unit is continuously adjustable.